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#### **ARTICLE**

## **Simple models for macro-parasite distributions in hosts**

 $\bullet$  Gonzalo Maximiliano Lopez<sup>\*,1,2</sup> and  $\bullet$  Juan Pablo Aparicio<sup>1,3</sup>

<sup>1</sup>Instituto de Investigaciones en Energía no Convencional, Consejo Nacional de Investigaciones Científicas y Técnicas, Universidad Nacional de Salta, Salta, Argentina.

<sup>2</sup>Departamento de Matemática, Facultad de Ciencias Exactas, Universidad Nacional de Salta, Salta, Argentina.

<sup>3</sup>Simon A. Levin Mathematical, Computational and Modeling Sciences Center, Arizona State University, Tempe-AZ, USA. ⋆Corresponding author. Email:<gonzalo.maximiliano.lopez@gmail.com>

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#### **Abstract**

The Negative binomial distribution is the most used distribution to model macro-parasite burden in hosts. However, reliable maximum likelihood parameter estimation from data is far from trivial. No closed formula is available and numerical estimation requires sophisticated methods. Using data from the literature, we show that simple alternatives to negative binomial, like zero-inflated geometric or hurdle geometric distributions, produce in some cases a better fit to data than the negative binomial distribution. We derived simple closed formulas for the maximum likelihood parameter estimators which constitutes a significant advantage of these distributions over the negative binomial distribution.

**Keywords**: Hurdle geometric distribution; Macroparasite, Maximum likelihood estimation; Negative binomial distribution; Zero-inflated geometric distribution;

## **1. Introduction**

Macroparasites usually present over-dispersed distributions, that is, a few hosts harbor many parasites, while the rest of the hosts are practically free of parasites (see, for example,Crofton, [1971;](#page-10-0) Gourbière *et al.,* [2015;](#page-10-1) Seo *et al.,* [1979\)](#page-11-0). The most used distribution to describe the distribution of parasites is the negative binomial (Bliss & Fisher, [1953;](#page-10-2) Shaw *et al.,* [1998\)](#page-11-1) which provides an accurate description of the observations.

However, in many cases, the negative binomial distribution (or other similar distributions like the log-series and Polya–Eggenberger (Crofton, [1971;](#page-10-0) Seo *et al.,* [1979\)](#page-11-0)) cannot account for the "excess" of zeros observed. A simple solution widely used is to consider zero-inflated distributions (Greene, [1994;](#page-10-3) Hall, [2000;](#page-10-4) Lambert, [1992\)](#page-10-5).

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The negative binomial distribution, denoted in the following by NB(*m*, *k*), is a two parameters distribution, the mean burden of parasites in the host population *m* and the dispersion parameter *k* which is related to the degree of overdispersion of the distribution (Bliss & Fisher, [1953\)](#page-10-2). Moreover, it can be shown that the limiting distribution of the NB(*m*, *k*) distribution, as  $k \to \infty$ , is a Poisson distribution with parameter *m*, and NB(*m*, *k*) distribution is a geometric distribution with parameter  $\frac{1}{m+1}$  when  $k = 1$ .

One problem with the negative binomial distribution is parameter estimation from the observations. The method of moments estimation is simple but not always precise (Clark & Perry, [1989\)](#page-10-6). Maximum likelihood estimation provides one of the best parameters estimation (Piegorsch, [1990\)](#page-10-7) but for the negative binomial distribution there is no a closed formula for the parameter estimates in terms of the observations and maximum likelihood estimates should be obtained numerically which presents various complexities (Bandara *et al.,* [2019;](#page-10-8) Dai *et al.,* [2013\)](#page-10-9).

In this article, we show simpler alternatives to the negative binomial distribution which describe the observations equally well, and in some cases provide a more precise description, but with the significant advantage that exist closed-form expressions for the maximum likelihood parameter estimators.

## **2. Zero-inflated (deflated) distributions and hurdle distributions**

The distribution of parasites in hosts is often over-dispersed, that is, there tend to be a small number of hosts who harbor very large burdens while the majority of hosts harbor low burdens. It is colloquially said that parasite's distributions follow the 20-80 rule (Woolhouse *et al.,* [1997\)](#page-11-2), that is, 20% of the individuals account for the 80% of the parasite burden. The negative binomial distribution offers such over-dispersed distribution, but in some cases, an excess of zeros is observed for which the distribution fail to account. A simple and widely used solution is to consider zeroinflated (in some cases zero-deflated, Dietz & Böhning [\(2000\)](#page-10-10)) distribution and hurdle distribution (Min & Agresti, [2005;](#page-10-11) Welsh *et al.,* [1996\)](#page-11-3).

#### <span id="page-1-0"></span>**2.1 Zero-inflated (deflated) distributions**

A discrete random variable *Y* follows a zero-inflated (deflated) distribution if its probability mass function (pmf ) is given by (Johnson *et al.,* [2005\)](#page-10-12),

<span id="page-1-1"></span>
$$
P(Y = \gamma) = \begin{cases} \pi + (1 - \pi)p(\gamma; \theta) & \gamma = 0 \\ (1 - \pi)p(\gamma; \theta) & \gamma \ge 1 \end{cases}
$$
 (1)

where *p* is the pmf of a given base distribution and  $\theta$  is a parameters vector. For example,  $\theta$  may include the mean (μ) and variance (σ<sup>2</sup>) of the base distribution. When  $\pi$  < 0 we have a zero-deflated distribution.

If  $G(z)$  is the probability generating function (pgf) of the base distribution, then the pgf of the corresponding zero-inflated (deflated) distribution is given by [\(ibid.\)](#page-10-12)

$$
F(z) = \pi + (1 - \pi)G(z)
$$
\n<sup>(2)</sup>

<span id="page-1-2"></span>From the pgf we may obtain the mean and the variance for the distribution

$$
E(Y) = (1 - \pi)\mu
$$
  
Var(Y) = (1 - \pi)\sigma<sup>2</sup> + \pi(1 - \pi)\mu<sup>2</sup> (3)

where  $\mu$ ,  $\sigma^2$  are the mean and variance of the base distribution, respectively. The dispersion index, or variance-to-mean ratio, is given by  $D = \frac{Var(Y)}{E(Y)}$  (Cox & Lewis, [1966\)](#page-10-13), then D can be written as

<span id="page-2-0"></span>
$$
D = \frac{\sigma^2}{\mu} + \pi\mu
$$
 (4)

where  $\sigma^2/\mu$  is the dispersion index of the base distribution. Therefore, from [\(4\)](#page-2-0), the zero-inflated distribution is more over-dispersed than the base distribution.

#### **2.2 Hurdle distributions**

Another common way to account for an excess of zeros is the hurdle distribution, where its pmf is given by (Johnson *et al.,* [2005\)](#page-10-12)

$$
P(Y = \gamma) = \begin{cases} \omega & \gamma = 0\\ (1 - \omega) \frac{p(y; \theta)}{1 - p(0; \theta)} & \gamma \ge 1 \end{cases}
$$
(5)

and  $p$ ,  $\theta$  are defined as in section [2.1.](#page-1-0)

If *G*(*z*) is the pgf for the base distribution, then the pgf for the hurdle distribution is [\(ibid.\)](#page-10-12)

$$
F(z) = \omega + (1 - \omega) \frac{G(z) - p(0; \theta)}{1 - p(0; \theta)}
$$
(6)

<span id="page-2-1"></span>and therefore, the mean and the variance of the hurdle distribution is,

$$
E(Y) = \alpha \mu
$$
  
Var(Y) =  $\alpha \sigma^2 + \alpha (1 - \alpha) \mu^2$  (7)

where  $\alpha = \frac{1-\omega}{1-\omega}$  $\frac{1-\omega}{1-p(0;\theta)}$ , and μ, σ<sup>2</sup> are the mean and variance of the base distribution, respectively. Finally the dispersion index for the hurdle distribution is given by

$$
D = \frac{\sigma^2}{\mu} + (1 - \alpha)\mu \tag{8}
$$

If  $ω > p(0; θ)$  the hurdle distribution is more over-dispersed than the base distribution.

## **3. Parameter estimation and Maximum likelihood**

A simple, but in general inaccurate, way to fit the parameters of a distribution from a sample consist of the use of the method of moments. For example, the negative binomial distribution has two parameters that can be expressed in terms of the two first moments. While this method is quite simple, do not provide a reliable fit (Clark & Perry, [1989;](#page-10-6) Piegorsch, [1990\)](#page-10-7). Maximum likelihood estimation (mle) is the most reliable method (Piegorsch, [1990\)](#page-10-7), but it does not always produce closedform expression, and the parameter estimations need to be obtained numerically, a task far from trivial for the negative binomial distribution (Bandara *et al.,* [2019;](#page-10-8) Bliss & Fisher, [1953;](#page-10-2) Dai *et al.,* [2013\)](#page-10-9). In the following, we present the problem of maximum likelihood parameter estimation for zero-inflated and hurdle distributions.

#### **3.1 Maximum likelihood estimation for zero-inflated (deflated) and hurdle distributions**

#### **3.1.1 Zero-inflated (deflated) distribution**

As in section [2.1](#page-1-0) we denote by θ to the vector of parameters of the base distribution, and therefore the set of parameters for the zero-inflated (deflated) distribution is  $(π, θ)$ .

Let  $y_i$  denote the *i*th observation,  $i = 1, \ldots, N$ , where  $N$  denote the total number of observations in the sample and  $N_0$  is the number of units with zero counts, then the  $log$ -likelihood function is given by

$$
\ln L(\pi, \theta) = \sum_{i=1}^{N} \ln P(Y = y_i)
$$
  
=  $N_0 \ln [\pi + (1 - \pi)p_0] + (N - N_0) \ln(1 - \pi) + \sum_{y_i \ge 1} \ln p_{yi}$  (9)

<span id="page-3-3"></span><span id="page-3-1"></span>where  $p_{\gamma_i} = p(\gamma_i; \theta)$ . Maximizing  $\ell = \ln L$  for  $(\pi, \theta)$  we obtain the following system of equations,

$$
\frac{\partial \ell}{\partial \pi} = \frac{N_0 (1 - p_0)}{\pi + (1 - \pi) p_0} - \frac{N - N_0}{1 - \pi} = 0
$$
\n
$$
\frac{\partial \ell}{\partial \theta_i} = \frac{N_0 (1 - \pi) \frac{\partial p_0}{\partial \theta_i}}{\pi + (1 - \pi) p_0} + \sum_{\gamma_i \ge 1} \frac{\frac{\partial p_{\gamma_i}}{\partial \theta_i}}{p_{\gamma_i}} = 0
$$
\n(10)

#### **3.1.2 Hurdle distributions**

The log-likelihood function for the hurdle distribution is given by

$$
\ln L(\omega, \theta) = \sum_{i=1}^{N} \ln P(Y = y_i)
$$
  
=  $N_0 \ln \omega + (N - N_0) \ln \left( \frac{1 - \omega}{1 - p_0} \right) + \sum_{\gamma_i \ge 1} \ln p_{\gamma_i}$  (11)

<span id="page-3-2"></span>and therefore the parameter values estimates are obtained from the following system

$$
\frac{\partial \ell}{\partial \omega} = \frac{N_0}{\omega} - \frac{N - N_0}{1 - \omega} = 0
$$
\n
$$
\frac{\partial \ell}{\partial \theta_i} = \frac{(N - N_0) \frac{\partial p_0}{\partial \theta_i}}{1 - p_0} + \sum_{\gamma_i \ge 1} \frac{\frac{\partial p_{\gamma_i}}{\partial \theta_i}}{p_{\gamma_i}} = 0
$$
\n(12)

## **4. Maximum likelihood for the negative binomial distribution and two simple alternatives.**

The probability mass function for the negative binomial distribution is

<span id="page-3-0"></span>
$$
P(Y = \gamma) = \frac{\Gamma(\gamma + k)}{\Gamma(\gamma + 1)\Gamma(k)} q^k (1 - q)^\gamma
$$
\n(13)

where  $0 \leq q \leq 1$  and  $k > 0$ .

Suppose we have data  $\gamma_1, \ldots, \gamma_N$  sampled from a negative binomial distribution [\(13\)](#page-3-0). Differentiating the log-likelihood function  $\ell = \ln L$  partially and setting them equal to zero yields the following system of equations

$$
\frac{\partial \ell}{\partial q} = \frac{Nk}{q} - \frac{mN}{1-q} = 0
$$
\n
$$
\frac{\partial \ell}{\partial k} = \left[ \sum_{i} \psi(y_i + k) \right] - N\psi(k) + N \ln q = 0
$$
\n(14)

where *m* is the mean of model [\(13\)](#page-3-0) and  $\psi(\gamma) = \frac{\Gamma'(\gamma)}{\Gamma(\gamma)}$  $\frac{\Gamma(y)}{\Gamma(y)}$  is the digamma function. Substituting in the second equation  $q = \frac{k}{m+k}$  (obtained from the first equation) we obtain

<span id="page-4-0"></span>
$$
\left[\sum_{i} \psi(\gamma_i + k)\right] - N\psi(k) + N\ln\left(\frac{k}{m+k}\right) = 0\tag{15}
$$

This equation cannot be solved for *k* in a closed form and must be solved numerically. Iterative techniques as Newton-Raphson method can be used, but this method may fail to find the mle value. Finding the mle value is a challenge, since we could not obtain the root or obtain more than one for the equation [\(15\)](#page-4-0) (Clark & Perry, [1989;](#page-10-6) Dai *et al.,* [2013;](#page-10-9) Piegorsch, [1990;](#page-10-7) Saha & Paul, [2005;](#page-11-4) Willson *et al.,* [1984\)](#page-11-5).

#### **4.1 Zero-inflated geometric distribution**

The geometric distribution is a special case of the negative binomial distribution for *k* = 1, and then, its pmf is given by

$$
P(X = x) = q(1 - q)^{x}
$$
\n<sup>(16)</sup>

where  $x = 0, 1, 2, \ldots$  and  $0 \le q \le 1$ . The mean is  $\frac{1-q}{q}$  while the variance is  $\frac{1-q}{q^2}$ .

From [\(1\)](#page-1-1) the corresponding zero-inflated (deflated) distribution is

$$
P(Y = \gamma) = \begin{cases} \pi + (1 - \pi)q & \gamma = 0 \\ (1 - \pi)q(1 - q)^\gamma & \gamma \ge 1 \end{cases}
$$
(17)

Mean and variance are given by [\(3\)](#page-1-2),

$$
E(Y) = (1 - \pi) \frac{(1 - q)}{q}
$$
  
Var(Y) =  $(1 - \pi) \frac{(1 - q)}{q^2} [1 + \pi(1 - q)].$  (18)

The dispersion index for the zero-inflated (deflated) geometric distribution is always greater than one, and therefore this distribution is always over-dispersed.

#### **4.1.1 Maximum likelihood estimation**

The system of likelihood equations, according to [\(10\)](#page-3-1), is given by

$$
\frac{\partial \ell}{\partial \pi} = \frac{N_0(1-q)}{\pi + (1-\pi)q} - \frac{N - N_0}{1 - \pi} = 0
$$
\n
$$
\frac{\partial \ell}{\partial q} = \frac{N_0(1-\pi)}{\pi + (1-\pi)q} + \frac{N - N_0}{q} - \frac{mN}{q} = 0
$$
\n(19)

Therefore, the maximum likelihood estimators for  $\pi$  and *q* are

$$
\hat{\pi} = \frac{mN_0 - N + N_0}{mN - N + N_0}
$$
\n
$$
\hat{q} = \frac{N - N_0}{mN}
$$
\n(20)

which is expressed in terms of the observed sample mean *m*, the sample size *N* and the number of zeros in the sample  $N_0$ .

#### **4.2 Hurdle geometric distribution**

The hurdle distribution for the geometric distribution is given by

$$
P(Y = \gamma) = \begin{cases} \omega & \gamma = 0\\ (1 - \omega) \frac{q(1 - q)^{\gamma}}{1 - q} & \gamma \ge 1 \end{cases}
$$
 (21)

Mean and variance are obtained from [\(7\)](#page-2-1)

$$
E(Y) = \frac{(1 - \omega)}{q}
$$
  
Var(Y) = 
$$
\frac{(1 - \omega)}{q^2} [1 + (\omega - q)]
$$
 (22)

The dispersion index for the hurdle geometric distribution is always greater than one, and therefore this distribution is always over-dispersed.

#### **4.2.1 Maximum likelihood estimation**

According to [\(12\)](#page-3-2) the system of likelihood equations is given by

$$
\frac{\partial \ell}{\partial \omega} = \frac{N_0}{\omega} - \frac{N - N_0}{1 - \omega} = 0
$$
\n
$$
\frac{\partial \ell}{\partial q} = (N - N_0) \left( \frac{1}{1 - q} + \frac{1}{q} \right) - \frac{mN}{1 - q} = 0
$$
\n(23)

therefore, the maximum likelihood estimators for ω and *q* are given by

$$
\hat{\omega} = \frac{N_0}{N}
$$
  
\n
$$
\hat{q} = \frac{N - N_0}{Nm}
$$
\n(24)

Like in the previous case, maximum likelihood estimators are expressed in terms of the observed sample mean *m*, the sample size N and the number of zeros in the sample  $N_0$ .

Note that by the reparameterization  $\omega = \pi + (1 - \pi)q$ , the probability mass functions of the zeroinflated geometric and hurdle geometric models coincide. On the other hand the pair  $\left(\frac{\hat{\omega}-\hat{q}}{1-\hat{q}},\hat{q}\right)$ is a maximum of the log-likelihood function [\(9\)](#page-3-3). Therefore we can obtain that the corresponding Akaike's information criterion values of both models will be the same.

Due to these facts, the fit of the data by both models will be the same.

## **5. Applications**

#### **5.1 Study of frequency distribution of** *Ascaris lumbricoides* **infection**

The nematode *Ascaris lumbricoides* is one of the most common intestinal parasites of humans. It is prevalent in tropical and temperate populations where poverty and lack of sanitation is common (Pullan & Brooker, [2012\)](#page-10-14).

Burden of infestation is computed using the number of parasites in each host of the sample. At the present time, this type of study is no longer conducted and we will use the results from Seo *et al.* [\(1979\)](#page-11-0). He studied six rural populations in Korea where an endemic situation was observed.

The samples obtained from each rural population were denoted by A, B, C, D, E and F respectively. These samples are over-dispersed (see Table [1\)](#page-7-0) and can be fitted by a negative binomial distribution (see Figure [1\)](#page-6-0).

<span id="page-6-0"></span>

**Figure 1.** Fitting the parasite counts data (black) by NB (red) and ZIG (blue) distribution for Seo et al. [\(ibid.\)](#page-11-0) data set. Except in the first case, the simple zero-inflated geometric distribution fit the data as well as the negative binomial distribution (see Table [1\)](#page-7-0).

In Figure [1](#page-6-0) we show the observed (black) and expected values of the fitted models (negative binomial and zero-inflated geometric). In addition, Table [1](#page-7-0) includes the maximum likelihood estimations, the chi-squared statistics for goodness-of-fit (D'Agostino, [2017\)](#page-10-15), their corresponding *p*-values, and Akaike's information criterion (AIC) (Konishi & Kitagawa, [2008\)](#page-10-16). As we see, the zero-inflated geometric distribution fit the data as well as the negative binomial distribution in most cases. The AIC results show that the negative binomial and zero-inflated geometric models produce a similar fit. Indeed, the fit in Figure [1](#page-6-0) improves the results obtained by negative binomial distribution in samples E and F. On the other hand, using the AIC, the geometric zero-inflated model showed the best performance in samples C, E and F. Hence, the zero-inflated geometric distribution,  $ZIG(\pi, q)$ , is a suitable candidate model to fit such data.

<span id="page-7-0"></span>

**Table 1.** Parameters of NB and ZIG distributions calculated from observed Seo et al. [\(1979\)](#page-11-0) data and results of chi-squared test and AIC

### **5.2 Parasite distribution in crabs**

Crofton (Crofton, [1971\)](#page-10-0) contributed significantly to the study of parasite distributions in hosts. In his works he observed that over-dispersion is one of the main characteristics of parasite-host distributions.

Analyzing data from Hynes & Nicholas [\(1963\)](#page-10-17) of six samples (A to F) of the parasitic infection of the crustacean *Gammarus pulex*, by the parasite acanthocephalan *Polymorphus minutus*, Crofton showed that the negative binomial distribution provides a good fit to the data.

<span id="page-8-0"></span>

**Figure 2.** Fitting the parasite counts data (black) by NB (red) and ZIG (blue) distribution for data in parasite in crabs (Crofton, [1971\)](#page-10-0). Zero-inflated (deflated) geometric distribution fit the data as well or better than the negative binomial distribution (see Table [2\)](#page-9-0).

In Figure [2](#page-8-0) we compare the fit to the data analyzed by Crofton using the negative binomial distribution and the zero-inflated (deflated) geometric distribution. In most cases our simple proposal provides a better fit than the negative binomial distribution.

Based on the chi-square goodness-of-fit test and the AIC reported in Table [2](#page-9-0) we conclude that the zero-inflated (deflated) geometric distribution provides a fit of the data as good as the negative binomial distribution.

<span id="page-9-0"></span>

**Table 2.** Parameters of NB and ZIG distributions calculated from observed of parasite in crabs data (Crofton, [1971\)](#page-10-0) and results of chi-squared test and AIC

## **6. Discussion and Conclusions**

The Negative binomial distribution is widely used to describe parasite burden in populations because this distribution often provides a good fit of the observations which can be improved by the corresponding zero-inflated (deflated) distribution (Crofton, [1971;](#page-10-0) Seo *et al.,* [1979\)](#page-11-0).

However, parameters estimation is far from trivial, and maximum likelihood estimates must be found always numerically. Simple numerical methods (as the Newton method, Atkinson [\(2008\)](#page-10-18)) are not easy to implement as there is not a closed expression for the derivative of the Gamma function and generally fail if the starting value is not chosen appropriately (Bandara *et al.,* [2019\)](#page-10-8).

The Negative binomial distribution may also fail to fit the zero counts (Crofton, [1971\)](#page-10-0). This issue may be overcome using the zero-inflated negative binomial distribution, however, parameters estimation by maximum likelihood is even more complex and also the AIC criteria penalize models with a larger number of parameters.

However zero-inflated geometric or hurdle geometric models are simpler alternatives to the negative binomial distribution, for which we found simple formulas for the maximum likelihood parameter estimates.

In the examples analyzed in this work zero-inflated geometric or hurdle geometric models present, in most cases, a similar fit to the data than the negative binomial model, and in some cases these models significantly improve the fit.

The AIC results show that the models are similar performance in both datasets.

However the major advantage of these models is not a little improvement in the data fitting but the fact that these models are simpler and with maximum likelihood parameter estimates easier to obtain than the negative binomial model.

For most of the sample considered, observations in the tail of the distribution may look too far from the expected values. However this fact does not necessarily indicates the need to consider other distributions. Since the samples are small, rare events in the tail, when observed acts like outliers given too much weight to this rare observation. The simulations presented in the Appendix are consistent with this explanation.

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#### **Conflicts of Interest**

The authors declare no conflict of interest.

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## <span id="page-12-0"></span>**Appendix**

As we show in Figure [1,](#page-6-0) some observations are not close to the predicted value obtained from the best fitted negative binomial distribution. Here we show that even for the case of the two largest samples (*n* = 540 and *n* = 136, see Table [1\)](#page-7-0) the observations are compatible with a negative binomial distribution. In each case, we produced 1000 simulated samples of sizes *n* = 540 and *n* = 136, drawed from the best fitted negative binomial.

The simulation results are shown in Figure [3](#page-12-1) where the simulated samples are in black dots and the Seo *et al.* [\(1979\)](#page-11-0) samples in red diamonds.

<span id="page-12-1"></span>

**Figure 3.** A and B samples of Seo et al. [\(ibid.\)](#page-11-0) in red diamonds and the simulated samples in black dots.